

List of Contents

NUMBER 1

- | | | |
|---|-----|---|
| I.A. Bonev and J. Ryu | 1 | A geometrical method for computing the constant-orientation workspace of 6- <i>PRRS</i> parallel manipulators |
| I.A. Bonev and J. Ryu | 15 | A new approach to orientation workspace analysis of 6-DOF parallel manipulators |
| A.K. Dhingra, A.N. Almadi and D. Kohli | 29 | Closed-form displacement analysis of 10-link 1-DOF mechanisms: part 1 – general framework |
| A.K. Dhingra, A.N. Almadi and D. Kohli | 57 | Closed-form displacement analysis of 10-link 1-DOF mechanisms: Part 2 – polynomial solutions |
| J. Murin | 77 | A machine aggregate with hydrodynamic power transmission at periodic loading |
| J. Murin | 93 | A controlled machine aggregate with hydrodynamic power transmission |
| J.E. Baker | 105 | The axodes of the Bennett linkage |
| J.E. Baker | 117 | On the feasibility of overconstrained linkages having screw-joints with tangent-based pitch |
| Y. Yu, N.G. Naganathan and R.V. Dukkpati | 123 | A literature review of automotive vehicle engine mounting systems |
| Chang Zongyu, Zhang Ce, Yang Yuhu and Wang Yuxin | 143 | A study on dynamics of roller gear cam system considering clearances |

NUMBER 2

- | | | |
|-------------------------------------|-----|---|
| M. Caccarelli | 153 | ON HMM2000 – International symposium on history of machines and mechanisms |
| N.S. Vyas and D. Satishkumar | 157 | Artificial neural network design for fault identification in a rotor-bearing system |
| N.S. Vyas and A.L. Wicks | 177 | Reconstruction of turbine blade forces from response data |
| R.V. Dukkpati | 189 | Lateral stability analysis of a railway truck on roller rig |

- | | | |
|---|-----|--|
| F. Gao, X.-J. Liu and X. Chen | 205 | The relationships between the shapes of the workspaces and the link lengths of 3-DOF symmetrical planar parallel manipulators |
| R. Caracciolo and A. Trevisani | 221 | Simultaneous rigid-body motion and vibration control of a flexible four-bar linkage |
| C.-J. Wu and J. Angeles | 245 | The optimum synthesis of an elastic torque-compensating cam mechanism |
| G. Karsai | 261 | Method for the calculation of the combined motion time derivatives of optional order and solution for the inverse kinematic problems |
| A.K. Dhingra, A.N. Almadi and D. Kohli | 273 | Closed-form displacement and coupler curve analysis of planar multi-loop mechanisms using Gröbner bases |
| A. Vasiliu and B. Yannou | 299 | Dimensional synthesis of planar mechanisms using neural networks: application to path generator linkages |

NUMBER 3

- | | | |
|--|-----|---|
| S. Kapucu, G. Alici and S. Bayseç | 311 | Residual swing/vibration reduction using a hybrid input shaping method |
| R. Boudreau and C.M. Gosselin | 327 | La synthèse d'une plate-forme de Gough-Stewart pour un espace atteignable prescrit |
| O. Shai | 343 | The duality relation between mechanisms and trusses |
| O. Navarro, C.-J. Wu and J. Angeles | 371 | The size-minimization of planar cam mechanisms |
| C.-F. Chang | 387 | Synthesis of adjustable four-bar mechanisms generating circular arcs with specified tangential velocities |
| S.B. Nokleby and R.P. Podhorodeski | 397 | Reciprocity-based resolution of velocity degeneracies (singularities) for redundant manipulators |
| H.-K. Kim, S.-B. Choi and B.S. Thompson | 411 | Compliant control of a two-link flexible manipulator featuring piezoelectric actuators |

NUMBER 4

- | | | |
|---|-----|---|
| N. Lobontiu, M. Goldfarb and E. Garcia | 425 | A piezoelectric-driven inchworm locomotion device |
|---|-----|---|

G.K. Ananthasuresh	445	Design of fully rotatable, roller-crank-driven, cam mechanisms for arbitrary motion specifications
Y. Wang, W.J. Zhang and H.M.E. Cheung	469	A finite element approach to dynamic modeling of flexible spatial compound bar-gear systems
A.C. Rao and P.B. Deshmukh	489	Computer aided structural synthesis of planar kinematic chains obviating the test for isomorphism
R.V. Dukkupati and S. Narayana Swamy	507	Non-linear steady-state curving analysis of some unconventional rail trucks
G. Rodnay and E. Rimon	523	Isometric visualization of configuration spaces of two-degrees-of-freedom mechanisms
M.H.F. Dado, N.S. Al-Huniti and A. Karim Eljabali	547	Dynamic simulation model for mixed-loop planar robots with flexible joint drives

NUMBER 5

R. Kluge	561	Nachruf
J.S. Rao	563	A note on Jeffcott warped rotor
R.V. Dukkupati and S. Narayana Swamy	577	Lateral stability and steady state curving performance of unconventional rail trucks
T. Koetsier	589	On the prehistory of programmable machines: musical automata, looms, calculators
Z. Wang, Z. Wang, W. Liu and Y. Lei	605	A study on workspace, boundary workspace analysis and workpiece positioning for parallel machine tools
L. Fan, Q. Liao and C. Liang	623	A new method for reverse force analysis of a spatial three-spring system
J.S. Dai and J. Rees Jones	633	Interrelationship between screw systems and corresponding reciprocal systems and applications
N. Lobontiu	653	Distributed-parameter dynamic model and optimized design of a four-link pendulum with flexure hinges

NUMBER 6

J. Wojnarowski	671	Preface
T. Szkodny	673	The sensitivities of industrial robot manipulators to errors of motion models' parameters

M. Cichy and M. Konczakowski	683	Bond graph model of the IC engine as an element of energetic systems
C. Orlikowski	689	Deriving transfer functions from bond graphs by application of Grassmann algebra
T. Młynarski and K. Romaniak	709	The methodization of examination of the mechanisms of high structural complexity
J. Wojnarowski and S. Zawiślak	717	Modelling of mechanical system by means of matroids

Regular Papers

Z.H. Fong, F.C. Huang and H.S. Fang	725	Evaluating the inter-lobe clearance of twin-screw compressor by the iso-clearance contour diagram (ICCD)
C. Galletti and P. Fanghella	743	Single-loop kinematotropic mechanisms
D. Chablat and P. Wenger	763	Séparation des solutions aux modèles géométriques direct et inverse pour les manipulateurs pleinement parallèles
S. Yue, S.K. Tso and W.L. Xu	785	Maximum-dynamic-payload trajectory for flexible robot manipulators with kinematic redundancy

NUMBER 7

A. Karger	801	Singularities and self-motions of equiform platforms
T. Bialkan, M.K. Özgören, M.A.S. Arıkan and H.M. Baykurt	817	A kinematic structure-based classification and compact kinematic equations for six-dof industrial robotic manipulators
S. Doughty	833	Response of single degree of freedom mechanisms to base excitation
R.S. Kalnas and S. Kota	843	Incorporating uncertainty into mechanism synthesis
Y.-R. Hu and G. Vukovich	853	Position and force control of flexible joint robots during constrained motion tasks
J.R. Hewit and J.R. Morris	873	Disturbance observation control with estimation of the inertia matrix

- X. Zhang and Y.-Q. Yu** 883 Motion control of flexible robot manipulators via optimizing redundant configurations

NUMBER 8

- Z. Huang and J. Wang** 893 Identification of principal screws of 3-DOF parallel manipulators by quadric degeneration
- P.A. Simionescu and M.R. Smith** 913 Four- and six-bar function cognates and over-constrained mechanisms
- C. Tischler, A. Samuel and K. Hunt** 925 Selecting multi-freedom multi-loop kinematic chains to suit a given task
- K. Russell and R.S. Sodhi** 939 Kinematic synthesis of adjustable RRSS mechanisms for multi-phase motion generation
- A. Kahraman** 953 Free torsional vibration characteristics of compound planetary gear sets
- H. Zhou and E.H.M. Cheung** 973 Optimal synthesis of crank-rocker linkages for path generation using the orientation structural error of the fixed link
- J.-H. Kim, B.-S. Ryuh and G.R. Pennock** 983 Development of a trajectory generation method for a five-axis NC machine
- T. Lin, H. Wei and Z.H. Jun** 997 Das Prinzip automatisierter Kombination von Mechanismen und dessen Realisierung
The principle for automated connection of mechanisms and its realization

NUMBER 9

- X. Kong and C.M. Gosselin** 1009 Forward displacement analysis of third-class analytic 3-RPR planar parallel manipulators
- X.-S. Gao, C.-C. Zhu, S.-C. Chou and J.-X. Ge** 1019 Automated generation of Kempe linkages for algebraic curves and surfaces
- J.-Y. Liu, M.-H. Hsu and F.-C. Chen** 1035 On the design of rotating speed functions to improve the acceleration peak value of ball-screw transmission mechanism
- H.-S. Yan and R.-C. Soong** 1051 Kinematic and dynamic design of four-bar linkages by links counterweighing with variable input speed

- T.-Y. Lee and J.-K. Shim** 1073 Forward kinematics of the general 6-6 Stewart platform using algebraic elimination

NUMBER 10

- S. Zupan and I. Prebil** 1087 Carrying angle and carrying capacity of a large single row ball bearing as a function of geometry parameters of the rolling contact and the supporting structure stiffness
- T. Yeh, D.C.H. Yang and S.-H. Tong** 1105 Design of new tooth profiles for high-load capacity gears
- J. Kim and F.C. Park** 1121 Direct kinematic analysis of 3-RS parallel mechanisms
- V. Abadjiev** 1135 On the helical tooth flank synthesis of skew-axes gear pairs
- S.S. Balli and S. Chand** 1147 Synthesis of a five-bar mechanism with variable topology for motion between extreme positions (SYNFBVTM)
- N. Dechev, W.L. Cleghorn and S. Naumann** 1157 Multiple finger, passive adaptive grasp prosthetic hand

NUMBERS 11-12

- L.S. Guo and W.J. Zhang** 1175 Kinematic analysis of a rice transplanting mechanism with eccentric planetary gear trains
- R.-T. Tseng and C.-B. Tsay** 1189 Mathematical model and undercutting of cylindrical gears with curvilinear shaped teeth
- E.N. Haulin, A.A. Lakis and R. Vinet** 1203 Optimal synthesis of a planar four-link mechanism used in a hand prosthesis
- I.-M. Chen, G. Yang, C.T. Tan and S.H. Yeo** 1215 Local POE model for robot kinematic calibration
- V. Arakelian and M. Dahan** 1241 Partial shaking moment balancing of fully force balanced linkages
- N.-I. Kim and C.-W. Lee** 1253 Multi-axis vibration control of a slender structure by using Stewart platform manipulator
- L.-J. Xu, S.-W. Fan and H. Li** 1271 Analytical model method for dynamics of *N*-celled tetrahedron-tetrahedron variable geometry truss manipulators

- J.J. Parise, L.L. Howell** 1281 Ortho-planar linear-motion springs
and **S.P. Magleby**
- J. Jesús Cervantes-Sánchez,** 1301 On the kinematic design of the 5R planar, sym-
J. César Hernández-
Rodríguez and J. Angeles metric manipulator



